COLLEGE OF ENGINEERING, UC BERKELEY

NSF

Spine: Software Framework for Wireless Body Sensor Networks

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Background

Wireless Body Sensor Networks have the potential to revolutionize healthcare.

CHESS

SRID & EMBEDDED

They reduce cost and improve quality of care by reducing physical barriers to prevention, detailed monitoring and continuous real-time reporting.

However, the difficultly of application development is a large barrier to adoption. We aim to remedy this by providing tools for BSN application developers.

What is Spine?

Spine is a software framework that automates and simplifies common tasks in BSN application creation. It is based on a Java and TinyOS software stack.

- Extensible: Developers can define custom functions to extend node capability.
- Developer-focused: Common tasks are automated to allow for rapid application deployment.
- Communication Management: A TDMA schedule is dynamically assigned based on application requirements. Power Management: To save power, nodes are duty-cycled according to the communication schedule.

We have developed and tested many sample applications including a real-time posture classification system and a tool to monitor range of motion in post-operative patients.

Hardware

Sensors

Compatible with any 802.15.4 device Compatible with any Java-capable device. running TinyOS. We have tested two sensor devices built on the Tmote Sky.







Gateway

Motorola E680i.

We have tested various PCs and the

lava

Rio-senso



http://chess.eecs.berkeley.edu/

Reporting of real-time local function activation



Network Service Manager (NSM)

Service Requests

- Query node capabilities
- Query request progress
- Request data
- Request to push data

For example, to request the mean value of sensor s on node n over the last 10 seconds computed every second (t is the current time):					
n	meanValue	s	t-10	t	1

.....

A request for data follows the following generic format Node Id Function Id Parameters (determined by function definition

Events

NSM returns requested data asynchronously when it is ready. Data is identified by a unique identifier.

Error Handling

An application may pre-specify alternate actions in case a request cannot be completed. If unspecified, error notifications allow the application to choose actions based on current node status.

Local Sensing and Processing

The sensor nodes sample and buffer data according to the constraints of current data requests.

All node data requests are abstracted via functions.

Functions can simply return raw Return data from a sensor sensorValue (*id*) return <u>getSensorValue(*id*)</u> data or perform local processing. Return sensor1 value only if it is greater than sensor2 compare (id3- id2) Developers can define functions if (getSensorValue(id1) > getSensorValue(id2) return getSensorValue(id) that implement: Return the mean value of a data buffer senValue (id, start, end, interval)
counter = 0, total = 0
for (time = start; time <= end; time += interval)
total += gatSansorValue(id, time)</pre> Processing algorithms Logic to control communication counter++ return total/count Local storage

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